

# Grablink Base

Frame grabber for one base-configuration Camera Link camera



# At a Glance

- For one Camera Link Base or Lite configuration camera
- Directly compatible with hundreds of Camera Link cameras available on the market
- Supports PoCL, Power over Camera Link
- ECCO: Extended Camera Link cable length
- PCIe x1 bus: 200 MB/s sustained delivery bandwidth
- Feature-rich set of 10 digital IO lines
- Memento Event Logging Tool

# **Benefits**

# **ECCO: Extended Camera Link Cable Operation**

- Use longer, up to 15 meters long, Camera Link cables!
- Download this document for more information

# Directly compatible with hundreds of Camera Link cameras available on the market

Check out our camera compatibility page (in the Support menu) to download the relevant CamFiles

# General purpose I/O lines

- Compatible with a wide range of sensors and motion encoders.
- High-speed differential inputs: Quadrature motion encoder support up to 5 MHz.
- Isolated current-sense inputs: 5V, 12V, 24V signaling voltages accepted, up to 50 kHz, individual galvanic isolation up to 500VAC RMS.
- Isolated contact outputs.

# **High-performance DMA (Direct Memory Access)**

- Direct transfer into user-allocated memory and hardware boards that expose PCI addresses
- Hardware scatter-gather support
- 64-bit addressing capability

# Area-scan triggering capabilities

• A trigger is used to start the acquisition when the part is in position. Hardware triggers come from the Grablink's I/O lines. Software triggers come from the application.

- An optional trigger delay is available to postpone the acquisition for a programmable time.
- A trigger decimation function allows to skip some of the triggers.
- Camera exposure control allows the application to control the exposure time of the camera.
- When the acquisition starts, at the appropriate timing, the Grablink board generates a signal to control an illumination device connected to one of its output lines.

# Line-scan triggering capabilities

Grablink supports continuous web scanning (to inspect infinite, continuously moving surfaces without losing a single line) and discrete object scanning (to acquire the image of objects moving in front of the camera).

- A trigger is used to start the acquisition when the part is in position. Hardware triggers come from the board's I/O lines. Software triggers come from the application.
- After it is started, the acquisition either:
  - Continues indefinitely (for web inspection applications)
  - Continues for a programmable number of lines (to acquire the image of objects of a known length)
  - Continues until an end trigger is received (to acquire the image of objects of a variable length)
- An optional trigger delay is available to postpone the beginning of the acquisition for a programmable number of lines.

# Line-scan triggering capabilities

- The Grablink frame grabber controls the camera scanning rate based on the signals received from a motion encoder. When the parts move faster, the acquisition line rate of the camera increases. When the parts move slower, the acquisition line rate of the camera decreases.
- The Grablink boards interpret A/B signals from quadrature motion encoders to know in which direction (forward or backward) the part is moving.
- Optionally, the Grablink can be instructed to acquire lines only when the object is moving forward or only when the object is moving backward.
- A feature called Backward Motion Cancellation stops the acquisition when a backward motion is detected. The line acquisitior automatically resumes when the motion is again in the forward direction, at the exact place where the acquisition was interrupted.
- A Rate Converter allows the camera to acquire lines at any programmable resolution lower or higher than the resolution of the motion encoder. This gives the designer incredible freedom and flexibility during the development of the application.
- A Rate Divider allows the camera to acquire lines at a resolution lower than the resolution of the motion encoder. It divides the frequency of the incoming encoder signal by a programmable integer.

# Flexible line-scan camera operation with the rate converter.

- The rate converter is a smart, programmable frequency multiplier/divider.
- Used with motion encoders and line-scan cameras, it allows the user to choose the aspect ratio of the pixels in the image.
- It provides a way to calibrate the acquisition chain to easily reach square (1:1 aspect ratio) pixels.

# Windows and Linux drivers available

# **Applications**

# Machine Vision for the Electronic Manufacturing Industry

- High speed image acquisition for AOI, 3D SPI, 3D lead/ball inspection machines.
- Very high resolution line-scan image acquisition for Flat Panel Display inspection and solar cell inspection

# **Machine Vision for the General Manufacturing Industries**

- High frame rate image acquisition for inspection machines
- Line-scan image acquisition for surface inspection machines
- Line-scan image acquisition for textile inspection

# **Machine Vision for the Printing Industry**

• High speed line-scan image acquisition for printing inspection machines

# **Video Acquisition and Recording**

• High-frame-rate video acquisition for motion analysis and recording

# **Specifications**

# Mechanical

Format	Low profile, half length, 1-lane PCI Express card
Cooling method	Air-cooling, fanless
Mounting	For insertion in a low-profile or standard height, 1-lane or higher, PCI Express card slot
Connectors	• 'A' on bracket:
	<ul> <li>26-position Shrunk Delta Ribbon (SDR) socket</li> </ul>
	<ul> <li>Camera Link Base connector</li> </ul>
	• 'EXTERNAL I/O' on standard bracket:
	− 25-pin 2-row female sub-D connector
	<ul> <li>I/O lines and power output</li> </ul>
	• 'INTERNAL I/O' on PCB:
	<ul><li>26-pin 2-row 0.1" pitch pin header with shrouding</li></ul>
	<ul> <li>I/O lines and power output</li> </ul>
	• 'POWER INPUT' on module:
	<ul> <li>4-pin MOLEX power socket</li> </ul>
	<ul> <li>12 VDC power input for PoCL camera and I/O power</li> </ul>
Dimensions	L 167.65 mm x H 68.90 mm
	L 6.6 in x H 2.71 in
Weight	98 g, 3.46 oz
Host bus	
Standard	PCI Express 1.0
Link width	1 lane
Link speed	2.5 GT/s (PCIe 1.0)
Maximum payload size	1024 bytes
DMA	32- and 64-bit
Peak delivery bandwidth	256 MB/s
Effective (sustained) delivery bandwidth	<ul> <li>Up to 200 MB/s for a PCI Express payload size of 256 bytes</li> </ul>
	<ul> <li>Up to 180 MB/s for a PCI Express payload size of 128 bytes</li> </ul>
Power consumption	Max. 4.5 W; Typ. 3.8 W (0.34 A @ 3.3V;0.22 A @+12V)
Camera / video inputs	
Interface standard(s)	Camera Link 2.0
Connectors	One Shrunk Delta Ribbon (SDR) Miniature Camera Link (MiniCL)
ECCO - Extended Camera Link Cable Operation	ECCO
Number of cameras	One Base or Lite camera
Maximum aggregated camera data transfer rate	2.04 Gbit/s (255 MB/s)
Camera Link configuration	Base or Lite
Camera Link clock frequency	From 20 MHz up to 85 MHz
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PoCL (Power over Camera Link)	One PoCL SafePower compliant controller with overload, over-voltage and short-circuit protections
Camera types	Gray-scale and color (RGB and Bayer) cameras
	Area-scan and line-scan cameras
Area-scan camera control	
Trigger	Precise control of asynchronous reset cameras, with exposure control.
	Support of camera exposure/readout overlap.
	• Support of external hardware trigger, with optional delay and trigger decimation.
Strobe	<ul> <li>Accurate control of the strobe position for strobed light sources.</li> </ul>
	Support of early and late strobe pulses.
Line-scan camera control	
Scan/page trigger	Precise control of start-of-scan and end-of-scan triggers.
	<ul> <li>Support of external hardware trigger, with optional delay.</li> </ul>
	• Support of infinite acquisition, without missing line, for web inspection applications.
Line trigger	<ul> <li>Support for quadrature motion encoders, with programmable noise filters, selection o acquisition direction and backward motion compensation.</li> </ul>
	Rate Converter tool for fine control of the pixel aspect ratio.
	Rate Divider tool
Line strobe	Accurate control of the strobe position for strobed light sources.
On-board processing	
On-board memory	64 MB (32 MB for image data)
Image data stream processing	<ul> <li>Unpacking of 10-/12-/14-bit to 16-bit with selectable justification to LSb or MSb</li> </ul>
Input LUT (Lookup Table)	<ul> <li>Monochrome: 8-bit, 10-bit or 12-bit per pixel, up to 500 MPixel/s</li> </ul>
	• RGB: 3x8-bit per pixel, up to 125 MPixel/s
Bayer CFA to RGB decoder	<ul> <li>Advanced interpolation method using average and median functions on a 3x3 kernel</li> </ul>
	• Up to 125 MPixel/s
General Purpose Inputs and	d
Outputs	
Number of lines	10 I/O lines:
	• 2 differential inputs (DIN)
	• 4 isolated inputs (IIN)
	• 4 isolated outputs (IOUT)
Usage	<ul> <li>The input lines can be used by the acquisition channel as:</li> </ul>
	<ul> <li>Camera frame trigger source (area-scan only)</li> </ul>
	<ul> <li>Acquisition sequence trigger source (area-scan only)</li> </ul>
	<ul> <li>Camera line trigger source (line-scan only)</li> </ul>
	<ul> <li>Page acquisition trigger source (line-scan only)</li> </ul>
	<ul> <li>Page acquisition end trigger source (line-scan only)</li> </ul>
	- (Quadrature) motion encoder input (line-scan only)
	The IOUT 1 output line can be used by the acquisition channel as:
	- Illumination strobe output
	<ul> <li>All the input lines can be used as general purpose inputs</li> </ul>
	All the output lines can be used as general purpose outputs

Electrical specifications	<ul> <li>DIN: High-speed differential inputs compatible with ANSI/EIA/TIA-422/485 differential line drivers and complementary TTL drivers</li> </ul>
	• IIN: Isolated current-sense inputs with wide voltage input range up to 30V, compatible with totem-pole LVTTL, TTL, 5V CMOS drivers, RS-422 differential line drivers, potential free contacts, solid-state relays and opto-couplers
	IOUT: Isolated contact outputs compatible with 30V / 100mA loads
Filter control	Glitch removal filter available only on input lines used as trigger sources
	Configurable with five time constants:
	= 100 ns, 500 ns, and 2.5 µs for trigger / page trigger / page end trigger sources
	<ul> <li>40 ns, 100 ns, 200 ns, 500 ns, 1 μs, 5 μs, 10 μs for line trigger sources</li> </ul>
Power output	Non-isolated, +5V, 1A and +12V, 1A, with electronic fuse protection
Software	
Host PC Operating System	• Microsoft Windows 10, 8.1, 7 for x86 (32-bit) and x86-64 (64-bit) processor architectures
	• Linux for x86 (32-bit) and x86-64 (64-bit) processor architectures
	Refer to release notes for details
APIs	<ul> <li>MultiCam 32- and 64-bit binary libraries (Windows and Linux), for ISO-compliant C/C++ compilers</li> </ul>
Environmental conditions	
Operating ambient air temperature	0 to +50 °C / +32 to +122 °F
Operating ambient air humidity	10 to 90% RH non-condensing
Storage ambient air temperature	-20 to +70 °C/ -4 to +158 °F
Storage ambient air humidity	10% to 90% RH non-condensing
Certifications	
Electromagnetic - EMC standards	European Council EMC Directive 2004/108/EC
	United States FCC rule 47 CFR 15
EMC - Emission	• EN 55022:2010 Class B
	FCC 47 Part 15 Class B
EMC - Immunity	• EN 55024:2010 Class B
	• EN 61000-4-2
	• EN 61000-4-3
	• EN 61000-4-4
	• EN 61000-4-5
	• EN 61000-4-6
KC Certification	Korean Radio Waves Act, Article 58-2, Clause 3
Flammability	PCB compliant with UL 94 V-0
RoHS	European Union Directive 2015/863 (ROHS3)
REACH	European Union Regulation 1907/2006
WEEE	Must be disposed of separately from normal household waste and must be recycled according to local regulations
Ordering Information	



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